

ENS - Master MVA / Paris 6 - Master Maths-Bio

Tutorial 4

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Exercise

Around the neural field equation (NFE)

We consider a NFE on a compact domain $\Omega \subset \mathbb{R}^p$ with a sigmoid S nonlinearity:

$$\frac{d}{dt}V(x, t) = -V(x, t) + \int_{\Omega} w(x, y)S(V(y, t))dy.$$

1. We assume that $w \in C^0(\Omega^2, \mathbb{R})$. Prove existence / uniqueness of the solution in the space $C = C(\Omega, \mathbb{R})$. *Hint*: show that it is globally Lipschitz. (This implies that the solution is defined globally, ie on \mathbb{R} .)
2. Show that the nonlinearity is C^1 .

We focus on the case $w(x, y) = w_0 + w_1 \cos(x - y)$ on $\Omega = (-\pi, \pi)$

3. Write the equations satisfied by the equilibrium. Are they finite dimensional?
4. Write a simplified set of equations for the dynamics. *Hint*: decompose the space with the range of the integral convolutional operator.
5. Consider a stationary state. Can you study its stability despite the fact that the equations are infinite dimensional? (Can you find a case where you can...?)

1/ This is a consequence of Cauchy Lip. theorem. We check that the right-hand side $F(V)$ is globally Lipschitz by noting that $S_m := \sup S'(x) < \infty$. Hence

$\|F(V_1) - F(V_2)\|_\infty \leq (1 + S_m \|w\|_\infty) \|V_1 - V_2\|_\infty$. It implies that the NFE has a solution globally defined in time. This is a classical consequence of the Cauchy-Lipschitz theorem but not of the finite time explosion (because we are in infinite dimension). 2/ We focus on $G(V) = W \cdot S(V)$. From Taylor with integral reminder, we have

$S(V + U) - S(V) - US'(V) = \int_0^1 (1 - t) S^{(2)}(V + tU) U^2 dt$. This shows that $W \cdot S(V + U) - W \cdot S(V) - W \cdot US'(V) = \int_0^1 (1 - t) WS^{(2)}(V + tU) U^2 dt$. One can check that the linear operator $\mathbf{L} = U \rightarrow W \cdot US'(V)$ is continuous on \mathcal{C} and is thus the candidate for the differential of G at V . It remains to check that the integral term is $o(U)$.

The reminder is $\int_0^1 (1 - t) W \cdot S^{(2)}(V + tU) U^2 dt$ and its norm is bounded by $\sup_x S^{(2)}(x) \|w\|_\infty \|U\|^2 = o(U)$. This shows that G is differentiable.

3/ Stationary solutions are

$$V(x) = \int_\Omega w(x - y) S(V(y)) dy = w_0 \int_\Omega S(V) + w_1 \sin(x) \int_\Omega \sin S(V) + w_1 \cos(x) \int_\Omega \cos S(V).$$

Hence, there are v_0, v_1, v_2 so that $V(x) = v_0 + v_1 \cos + v_2 \sin$. We can plug this expression in the integral equation and project on 1, cos, sin. It gives 3 equations in v_0, v_1, v_2 . The problem is 3d. 4) Same technics as 3). 5) Let us imagine that $V^{eq} = 0$ is a stationary solution. In the general case, one has to adapt a bit the technics but it is essentially the same idea. Then, the stability is linked to the spectrum of the linearized operator $LU = -U + W \cdot (S'(0)U)$. Hence, we focus on the second term. This operator is of rank 3. In fact, in the orthogonal of $\text{Vect}(1, \cos, \sin)$, it is zero. One can thus restrict the study on $\text{Vect}(1, \cos, \sin)$ where we find that the spectrum is $\{2\pi w_0, \pi w_1\}$. All in all, the spectrum of the linearized operator is $\{-1, -1 + 2\pi w_0, -1 + \pi w_1\}$. The stability analysis is then straightforward.

Exercise

Around the neural field equation of Amari type

We consider a neural field equation on the real line

$$\frac{d}{dt} V(x, t) = -V(x, t) + \int_{\mathbb{R}} w(x - y) S(V(y, t)) dy + h$$

in the case where $S(v) = \mathbf{1}_{v>0}$ is the Heaviside function and $h \in \mathbb{R}$.

The **connectivity kernel** $w \in \mathcal{C}(\mathbb{R}, \mathbb{R})$ is a real **even** function which is integrable on \mathbb{R} . We define $W(x) = \int_0^x w$ and $W_\infty := \lim_{x \rightarrow \infty} W(x)$.

We further define $R(V) = \{x, V(x) > 0\}$. An equilibrium V^{eq} is said **localized** if

$R(V^{eq}) = (a_1, a_2)$ with $a_i \in \mathbb{R}$. In this case, we can always assume $a_1 = 0$ by translation invariance.

1. An equilibrium V^{eq} such that $R(V^{eq}) = \emptyset$ exists if and only if $h \leq 0$.
2. An equilibrium V^{eq} such that $R(V^{eq}) = \mathbb{R}$ exists if and only if $2W_\infty > -h$.
3. We here assume the following behavior of W on \mathbb{R}^+ . W is strictly increasing towards its maximal value W_M and is then strictly decreasing and converging to $W_\infty < 0$. Show that an equilibrium V^{eq} such that $R(V^{eq}) = (0, a)$ with $a > 0$ exists if and only if $h < 0$ and $W(a) + h = 0$.
4. Find solutions with a periodic support, namely $R(V^{weq}) = \cup_{n=-\infty}^{\infty} [-b + nL, b + nL]$ under the restriction $2b < L$. Find an equation satisfied by b .
5. Find traveling fronts $V(x, t) = U(x - ct)$ where the speed c and the waveform U have to be determined. One can introduce traveling wave coordinate $\xi = x - ct$ and assume $c > 0$.
6. **Interface dynamics.** We assume that a solution is such that $R(V(x, t)) = (-a(t), a(t))$ and that $0 \leq V_0(x) \leq 1$. We assume that V_0 is even. Find an equation satisfied by a in the case $h = 0$.
7. In the case of a non-convolutional kernel, $w(x, y) = e^{-|x-y|}(1 + a \cos(y))$, $0 < a < 1$, find the number of stationary solutions as function of their width.

This behavior is called **snaking** of stationary solutions.

1/ If such solution exists then $V(x) = h$ which requires $h \leq 0$. On the contrary, if $h \leq 0$, then $V(x) = h$ is a stationary solution of the NFE.

2/ If there is such solution then it satisfies $V(x) = \int_{\mathbb{R}} w(x-y)dy + h = 2W_\infty + h > 0$. On the contrary, if $2W_\infty + h > 0$, then $V(x) = 2W_\infty + h$ is such solution.

3/ A **localised** solution is such that

$V(x) = \int_0^a w(x-y)dy + h = W(x) - W(x-a) + h$. This solution is continuous, hence it satisfies $V(0) = V(a) = 0$ which implies $W(a) + h = 0$. Finally, $V \rightarrow h$ when $x \rightarrow \infty$ which implies $h \leq 0$. On the contrary, when $W(a) = -h$ holds and $h \leq 0$, one finds $V(a) = V(0) = 0$. Moreover, such V is C^1 . Using the hypothesis on the shape of W , one can prove that $V(x) = W(x) - W(x-a) + h$ is positive on the interval $(0, a)$ and negative elsewhere, provided that $h \leq 0$.

4/ These solutions take the form

$$U(x) = \sum_{n \in \mathbb{Z}} \int_{-b+nL}^{b+nL} w(x-y)dy + h = \sum_{n \in \mathbb{Z}} (W(x+b+nL) - W(x-b+nL)) + h.$$

The threshold condition reads $U(\pm b + nL) = 0$. This gives

$$h + \sum_{n \in \mathbb{Z}} (W(2b+nL) - W(nL)) = 0.$$

5/ the solution satisfies $U_f(\xi) = e^{\xi/c} \left[\kappa - \frac{1}{c} \int_0^\xi e^{-y/c} (W_\infty - W(y)) dy \right]$. Assuming $c > 0$ and requiring boundedness implies $\kappa = \frac{1}{c} \int_0^\infty e^{-y/c} (W_\infty - W(y)) dy$. The traveling wave is thus of the form $U_f(\xi) = \frac{1}{c} \int_0^\infty e^{-y/c} (W_\infty - W(y + \xi)) dy$.

6/ By definition $V(\pm a(t), t) = 0$ hence $\pm x(t)a'(t) + \partial_t V(\pm a(t), t) = 0$ where we defined $\pm a(t) = \partial_x u(\pm a(t), t)$. One gets $a'(t) = -\frac{1}{\alpha(t)} [W(2a(t)) - \kappa]$. This equation is not well defined for $\alpha(t) = 0$. We now get an expression for α . We define $z(x, t) = \partial_x V(x, t)$ and find $\partial_t z(x, t) = -z(x, t) + w(x + a(t)) - w(x - a(t))$ which allows to find $\alpha(t) = u'_0(a(t))e^{-t} + e^{-t} \int_0^t e^s [w(a(t) + a(s)) - w(a(t) - a(s))] ds$. This gives us a closed system describing the evolution of a, α with the initial conditions $a(0) = l, \alpha(0) = u'_0(l)$ as long as $\alpha < 0$.

7) The width a of the solution satisfies $h + \int_0^a w(a, y) dy = 0$. Writing $W(x) = \int_0^x w(x, y) dy$, one finds for $x > 0$, $W(x) = 1 - e^{-x} \frac{a}{2} - e^{-x} + a \cos(x)/2 + a \sin(x)/2$. Hence, there are infinitely many a solution for $h \approx 1$.

Exercise

Normal form and center manifold

We consider $\frac{du}{dt} = \mathbf{A}u + \mathbf{R}(u, \mu)$. Let us write the Taylor expansion of \mathbf{R} for a given p :

$$\mathbf{R}(u) = \sum_{2 \leq q+l \leq p} \mathbf{R}_{ql}[u^{(q)}, \mu^{(l)}] + o(\|u\|^p), \quad \mathbf{R}_{01} = 0$$

with $\mathbf{R}_{ql} = \frac{1}{q!l!} \frac{\partial \mathbf{R}}{\partial u^q \partial \mu^l}$, $u^{(q)} \equiv (u, \dots, u) \in \mathcal{Z}_h^q$ and $\mu^{(l)} \equiv (\mu, \dots, \mu) \in (\mathbb{R}^{m_{par}})^l$.

1. Assume that there is a center manifold Ψ and that we perform a Normal form simplification on the center manifold with change of variable $u_c = v_0 + \Phi_\mu(v_0)$. Write the nonlinear mapping $v_0 \rightarrow u$. Write the equation satisfied by the combined change of variables (Hint: use the same technics as for the center manifold function Ψ).
2. (Difficult) Assume that we have a Hopf bifurcation. We write $v_0(t) = A(t)\zeta + \overline{A(t)\zeta}$ with $A \in \mathbb{C}$ where v_0 is the coordinate on the center manifold after the normal form transform. Assume that the normal form reads $\dot{A} = A(a\mu + b|A|^2) + O((|\mu| + |A|^2)^2)$. Finally write $u = v_0 + \tilde{\Psi}(v_0, \mu)$ and $\tilde{\Psi}(v_0, \mu) = \sum_{p,q,r} \Psi_{p,q,r} A^p \bar{A}^q \mu^r + \dots$. Show that $a = \langle \mathbf{R}_{11}(\zeta) + 2\mathbf{R}_{20}(\zeta, \Psi_{001}), \zeta^* \rangle$ and

$b = \langle 2\mathbf{R}_{20}(\zeta, \Psi_{110}) + 2\mathbf{R}_{20}(\bar{\zeta}, \Psi_{110}) + \mathbf{R}_{30}(\zeta, \zeta, \bar{\zeta}), \zeta^* \rangle$. For this, find the first terms Ψ_{001}, \dots by identifying the monomials of $\tilde{\Psi}$ in the equation derived in 1).

3. We consider the **Ring Model of orientation tuning** $\dot{V} = -V + J \star S_0(V)$ on the circle, ie $J \star S_0(V)(\theta) = \int_{-\pi}^{\pi} J(\theta - \theta') S_0(V(\theta')) d\theta'$, V is periodic and S_0 is a smooth bounded function such that $S_0(0) = 0$. Assume further that w is **even**.

1. Show that the vector field is equivariant w.r.t $T_t \cdot V(\theta) = V(\theta - t)$ and $R \cdot V(\theta) = V(-\theta)$. What is the group generated by T_t, R ?
2. (★★) Assume that there a Pitchfork bifurcation at $\mu = \mu_0$. Compute the normal form as function of the parameters of the model. For this, one has to adapt the previous question 2).

ATTENTION ICI NOTATIONS

1. we build a reduced equation for $u_c \in \mathcal{X}_c$ with the center manifold correction Ψ :

$$u = u_c + \Psi(u_c, \mu), \quad \Psi(u_c, \mu) \in \mathcal{Z}_h.$$

This reduced equation is

$$\frac{du_c}{dt} = \mathbf{A}u_c + P_c \mathbf{R}(u_c + \Psi(u_c, \mu), \mu).$$

Then, we apply a change of variable to u_c

$$u_c = v_0 + \Phi_\mu(v_0), \quad v_0 \in \mathcal{X}_c$$

to bring the reduced equation to a normal form given by:

$$\frac{dv_0}{dt} = \mathbf{A}|_{\mathcal{X}_c} v_0 + \mathbf{N}_\mu(v_0) + \rho(v_0, \mu),$$

where \mathbf{N}_μ is a polynomial of some degree p such that $\mathbf{N}_0(0) = 0$, $D_v \mathbf{N}_0(0) = 0$ and $\rho(v_0, \mu) = o(\|v_0\|^p)$. We write

$$u = v_0 + \tilde{\Psi}(v_0, \mu), \quad \tilde{\Psi}(v_0, \mu) \equiv \Phi_\mu(v_0) + \Psi(v_0 + \Phi_\mu(v_0), \mu) \in \mathcal{Z}$$

The nonlinear function $\tilde{\Psi}$ is solution of the next equations:

$$(NF) : \begin{cases} D_{v_0} \tilde{\Psi}(v_0, \mu) \mathbf{A}|_{\mathcal{X}_c} v_0 - \mathbf{A} \tilde{\Psi}(v_0, \mu) + \mathbf{N}_\mu(v_0) = \mathbf{Q}(v_0) \\ \mathbf{Q}(v_0) \equiv \Pi_p [\mathbf{R}(v_0 + \tilde{\Psi}(v_0, \mu), \mu) - D_{v_0} \tilde{\Psi}(v_0, \mu) \mathbf{N}_\mu(v_0)] \end{cases}$$

where Π_p is the operator which takes the first $p + 1$ terms in the Taylor expansion in

the variable v_0 .

2. Under these assumptions, we have that $\Sigma_0 = \{\pm i\omega\}$ and that the associated center subspace E_0 is two-dimensional spanned by the eigenvectors $\zeta, \bar{\zeta}$ associated with $i\omega$ and $-i\omega$, respectively. We set $\tilde{\Psi} \equiv \sum_{p,q,r} \Psi_{p,q,r} A^p \bar{A}^q \mu^r$. By identifying in (NF) the terms of order $O(\mu)$, $O(A^2)$, and $O(A\bar{A})$, we obtain

$$\begin{aligned} -\mathbf{L}\Psi_{2,0,0} &= \mathbf{R}_{0,1} \\ (2i\omega - \mathbf{L})\Psi_{2,0,0} &= \mathbf{R}_{2,0}(\zeta, \zeta) \\ -\mathbf{L}\Psi_{1,1,0} &= 2\mathbf{R}_{2,0}(\zeta, \bar{\zeta}) \end{aligned}$$

Here the operators \mathbf{L} and $2i\omega - \mathbf{L}$ are invertible so that the equation above are uniquely determined. Next we identify terms of order $O(\mu A)$ and $O(A^2 \bar{A})$ and find

$$\begin{aligned} (i\omega - \mathbf{L})\Psi_{1,0,1} &= -a\zeta + \mathbf{R}_{1,1}(\zeta) + 2\mathbf{R}_{2,0}(\zeta, \Psi_{0,0,1}) \\ (i\omega - \mathbf{L})\Psi_{2,1,0} &= -b\zeta + \mathbf{R}_{2,0}(\zeta, \Psi_{1,1,0}) + 2\mathbf{R}_{2,0}(\bar{\zeta}, \Psi_{2,0,0}) + 3\mathbf{R}_{3,0}(\zeta, \zeta, \bar{\zeta}) \end{aligned}$$

Since $i\omega$ is a simple isolated eigenvalue of \mathbf{L} , the range of $(i\omega - \mathbf{L})$ is of codimension 1, so that we can solve these equations, and determine $\Psi_{1,0,1}$ and $\Psi_{2,0,0}$, provided the right hand sides satisfy one solvability condition. It is this solvability condition which allows to compute the coefficients a and b . In the case when \mathbf{L} has an adjoint \mathbf{L}^* , acting in the dual space X^* , then the solvability condition is that the right hand sides are orthogonal to the kernel of the adjoint $(-i\omega - \mathbf{L}^*)$ of $(i\omega - \mathbf{L})$. The kernel of $(-i\omega - \mathbf{L}^*)$ is one-dimensional, just as the kernel of $(i\omega - \mathbf{L})$, spanned by $\zeta^* \in X^*$ that we choose such that $\langle \zeta, \zeta^* \rangle = 1$. Here $\langle \cdot, \cdot \rangle$ denotes the duality product between X and X^* . For example $a = \langle \mathbf{R}_{1,1}(\zeta) + 2\mathbf{R}_{2,0}(\zeta, \Psi_{0,0,1}), \zeta^* \rangle$.

3. By symmetry arguments, the bifurcation is of “pitchfork” type and the central part is given by $E_0 = \text{Vect}(\cos(2\cdot), \sin(2\cdot)) = \ker \mathbf{L}_{\mu_0}$ where $\mathbf{L}_{\mu} = -Id + \mu S'(\mu v_0^f(\mu))J$. We use complex coordinates $U_0 = A\zeta + c.c$ with $\zeta = e^{2i\theta}$ and $A \in \mathbb{C}$, the normal form is given by:

$$\dot{A} = A \left(\frac{\sigma - \sigma_0}{\sigma_0} + \chi_3 |A|^2 \right) + h. o. t.$$

We write $V(\theta, t) = v_0^f + \mathbf{U}_0 + \Psi(\mathbf{U}_0, \mu)$. The Taylor expansion reads

$$\Psi(\mathbf{U}_0, \mu) = \Psi_{20} A^2 + \bar{\Psi}_{20} \bar{A}^2 + \Psi_{11} A \bar{A} + \Psi_{30} A^3 + \bar{\Psi}_{30} \bar{A}^3 + \Psi_{21} A^2 \bar{A} + \bar{\Psi}_{21} A \bar{A}^2$$

We write $\mathbf{R}(\mathbf{U}, \mu) = -v_0^f - \mathbf{U} + \mathbf{J} \star S(\mu\mathbf{U} + \mu v_0^f) - \mathbf{L}_{\mu_0}$. We note that $D_{v_0} \tilde{\Psi}(v_0, \mu) \mathbf{A}|_{\mathcal{X}_c} v_0 = 0$. We look at the coefficient $A|A|^2$ in (NF), it satisfies

$$b\zeta - \mathbf{L}_{\mu_0} \Psi_{21} = 2\mathbf{R}_{20}(\zeta, \Psi_{11}) + 2\mathbf{R}_{20}(\bar{\zeta}, \Psi_{20}) + 3\mathbf{R}_{30}(\bar{\zeta}, \zeta, \zeta).$$

The coefficient A^2 gives

$$-\mathbf{L}_{\mu_0} \Psi_{20} = \mathbf{R}_{20}(\zeta, \zeta)$$

The coefficient $A\bar{A}$ gives

$$-\mathbf{L}_{\mu_0} \Psi_{11} = \mathbf{R}_{20}(\zeta, \bar{\zeta})$$

The coefficient A^3 gives

$$-\mathbf{L}_{\mu_0} \Psi_{30} = \mathbf{R}_{20}(\zeta, \Psi_{20}) + \mathbf{R}_3(\bar{\zeta}, \zeta, \zeta).$$

It remains to solve the above convolution equations. We write $e_n(\theta) = e^{2in\theta}$ and $J \star e_n = J_n e_n$. We find $\mathbf{R}_2(\zeta, \zeta) = \frac{1}{2} \mu_0^2 S^{(2)}(\mu_0 v_0^f) J \star \zeta^2$ hence

$\Psi_{20} = \alpha_{20} \zeta + \beta_{20} \bar{\zeta} + \frac{\mu_0^2 S^{(2)}(\mu_0 v_0^f) J_2}{2(-1 + \mu_0 S^{(1)}(\mu_0 v_0^f) J_2)} = \alpha_{20} \zeta + \beta_{20} \bar{\zeta} + \frac{\mu_0^2 S^{(2)}(\mu_0 v_0^f) J_2}{2(1 - J_2/J_1)}$. The final result is

$$b = \mu_0^3 J_1 \left[\frac{S^{(3)}(\mu_0 v_0^f)}{3} + \mu_0 S^{(2)}(\mu_0 v_0^f) \left(\frac{J_0}{1 - J_0/J_1} + \frac{J_2}{2(1 - J_2/J_1)} \right) \right]$$