

Basic knowledge for the MMN lectures

Romain Veltz

Team MathNeuro, INRIA Sophia Antipolis

E-mail: romain.veltz@inria.fr

1. Picard theorem(s)

We start with a very standard result that is the basis for most results in these notes. This first section is based on [[Viterbo, 2003](#)].

1.1. Basic results

Definition 1.1

A function $T : X \rightarrow X$ where (X, d) is a metric space is contracting iff $\forall x, y \in X$ $d(Tx, Ty) \leq k \cdot d(x, y)$ where $k < 1$.

Theorem 1.1 (*Picard*)

Let X be a complete metric space and $T : X \rightarrow X$ a contracting mapping. Then T has a unique fixed point i.e. the unique solution of the equation $T(y) - y = 0$.

Proof. Take $x_0 \in X$ and show that $(T^n x_0)_n$ is a Cauchy sequence hence convergent (in a complete space), its limit will be the solution of the fixed point equation. If $n \geq m$

$$d(T^n x_0, T^m x_0) \leq d(T^m(T^{n-m} x_0), T^m x_0) \leq k^m d(T^{n-m} x_0, x_0).$$

We have from the triangle inequality:

$$\begin{aligned} d(T^{n-m} x_0, x_0) &\leq \sum_{i=0}^{n-m-1} d(T^{i+1} x_0, T^i x_0) \leq \sum_{i=0}^{n-m-1} k^i d(T x_0, x_0) \\ &\leq \frac{1 - k^{n-m}}{1 - k} d(T x_0, x_0) \leq \frac{1}{1 - k} d(T x_0, x_0). \end{aligned}$$

This gives:

$$d(T^m x_0, T^n x_0) \leq \frac{k^m}{1 - k} d(T x_0, x_0)$$

which shows that $(T^n x_0)_n$ is a Cauchy sequence. ■

We provide without proof a version with parameters. To have a notion of differentiability, we need to assume that we work in a Banach space. Hence, if $p = 0$, X is a metric space and a closed subspace of a Banach space if $p > 0$. Also, if $p = 0$,

Λ is a metric space and an *open* subspace of a Banach space if $p > 0$. We consider a mapping $T \in C^p(X \times \Lambda, X)$ such that $x \rightarrow T(x, \lambda)$ is Lipschitz with constant $k(\lambda)$ where $\lambda \rightarrow k(\lambda)$ is continuous. We say that we have a C^p **map of contracting functions** if moreover $k(\lambda) < 1$.

Theorem 1.2 (Picard with parameters)

A C^p map of contracting functions on a space X has a family of fixed points $x(\lambda)$ where the map $\lambda \rightarrow x(\lambda)$ is C^p .

1.2. Applications, see [Chow and Hale, 1982, Franoise, 2005]

We work here in Banach spaces, *i.e.* complete normed vector space. Recall that a linear map $L \in \mathcal{L}(E, F)$ between Banach spaces is continuous iff $\|L\|_{\mathcal{L}(E, F)} \equiv \sup_{\|x\|_E \leq 1} \|Lx\|_F < \infty$.

Theorem 1.3 (Implicit functions theorem)

Let us consider two open sets U, V in Banach spaces E_1, E_2 and $f : U \times V \rightarrow F$ a C^k application with $k \geq 1$. We assume $f(x_0, y_0) = 0$ and $\frac{\partial f}{\partial y}(x_0, y_0) \in \mathcal{L}(E_2, F)$ has a **continuous** inverse. Then there are neighborhoods U' of x_0 , V' of y_0 and a mapping $\phi \in C^k(U', V')$ such that

$$\forall (x, y) \in U' \times V', f(x, y) = 0 \Leftrightarrow y = \phi(x).$$

Proof. For $\ddagger x \in B(x_0, r)$ and $y \in B(y_0, r')$, the mapping

$$T_x(y) = y - \left(\frac{\partial f}{\partial y}(x_0, y_0) \right)^{-1} f(x, y)$$

is continuous from $\overline{B(y_0, r')}$ to itself if r, r' are small enough. Indeed:

$$dT_x(y) = Id - \left(\frac{\partial f}{\partial y}(x_0, y_0) \right)^{-1} \frac{\partial f}{\partial y} f(x, y)$$

is close to zero hence we can chose r, r' small enough so that for all x in $B(x_0, r)$ and y in $B(y_0, r')$, we have $\|dT_x(y)\| \leq \frac{1}{2}$. Then it gives $\|T_x(y_0) - y_0\| = \left\| \left(\frac{\partial f}{\partial y}(x_0, y_0) \right)^{-1} f(x, y) \right\| \leq r'/2$ if r, r' are small enough. It follows that $T_x \left(\overline{B(y_0, r')} \right) \subset \overline{B(T_x(y_0), r'/2)} \subset \overline{B(y_0, r')}$ (strict inclusion). Hence, $T_x : \overline{B(y_0, r')} \rightarrow \overline{B(y_0, r')}$ is contracting and we conclude with the Picard theorem with parameters. ■

We also have a result to invert a nonlinear map.

\ddagger We use the definition $B(x_0, r) = \{x \in X \mid d(x, x_0) < r\}$

Theorem 1.4 (Inverse function theorem)

Let $\phi \in C^k(U, V)$ and $d\phi(x_0)$ has a bounded inverse. There are open sets U', V' containing x_0 and $y_0 = \phi(x_0)$ and a map $\psi \in C^k(V', U')$ such that $\phi \circ \psi = Id$.

Proof. We apply the previous theorem to $f(u, v) = v - \phi(v)$. ■

1.3. Cauchy-Lipschitz theorems

We consider $F : I \times \Omega \rightarrow E$ where Ω is an open set of a Banach space E and I is an open interval of \mathbb{R} . We want to solve

$$\dot{x} = F(t, x) \tag{1}$$

with the initial condition $x(t_0) = x_0 \in \Omega, t_0 \in I$.

Theorem 1.5 (Cauchy-Lipschitz)

We assume that F is continuous and Lipschitz in the second variable. Then for all $\tau \in I$ and $u_0 \in \Omega$ there exist $\delta, \alpha > 0$ such that the system

$$\begin{cases} \dot{x} = F(t, x), \\ x(t_0) = x_0 \in \Omega \end{cases}$$

has a unique solution defined on $]t_0 - \alpha, t_0 + \alpha[$ for all $x_0 \in B(u_0)$ and $t_0 \in]\tau - \delta, \tau + \delta[$.

Proof. Left in exercise, you may use the Picard theorem. ■

The theorem looks complicated in this form because we want that for t_0 in a neighborhood of τ and x_0 in a neighborhood of u_0 , the size 2α of the domain of definition is uniformly minored. We also give a version with parameters. Note that the initial condition can be taken as a parameter.

Theorem 1.6 (Cauchy-Lipschitz with parameters)

We assume that $F(\lambda, t, x)$ is in $C^k(\Lambda \times I \times \Omega, E)$ with $k \geq 0$, Lipschitz in the variable x and Λ satisfies the hypothesis of theorem 1.2. Let $x_\lambda(t; t_0, x_0)$ be the solution of

$$\begin{cases} \dot{x} = F(\lambda, t, x), \\ x(t_0) = x_0 \in \Omega \end{cases}$$

Then for all $(\lambda_0, \tau, u_0) \in \Lambda \times I \times \Omega$, there exist $\delta, \alpha > 0$ such that x_λ is defined on $]t_0 - \alpha, t_0 + \alpha[$ for all $(\lambda_0, t_0, x_0) \in B(\lambda_0, \delta) \times]\tau - \delta, \tau + \delta[\times B(u_0, \delta)$. Moreover, the map $(t, \lambda, t_0, x_0) \rightarrow x_\lambda(t; t_0, x_0)$ is C^k .

Up to the domain of definition, this theorem amounts to saying that $(t, \lambda, t_0, x_0) \rightarrow x_\lambda(t; t_0, x_0)$ is C^k .

Contents

1 Picard theorem(s)	1
1.1 Basic results	1
1.2 Applications, see [Chow and Hale, 1982, Franoise, 2005]	2
1.3 Cauchy-Lipschitz theorems	3

References

- [Chow and Hale, 1982] Chow, S.-N. and Hale, J. K. (1982). *Methods of Bifurcation Theory*, volume 251 of *Grundlehren der mathematischen Wissenschaften*. Springer New York, New York, NY.
- [Franoise, 2005] Franoise, J.-P. (2005). *Oscillations en biologie: analyse qualitative et modeles*. Number 46 in *Mathmatiques & applications*. Springer, Berlin New York.
- [Viterbo, 2003] Viterbo, C. (2003). *Equations differentielles et systemes dynamiques*. Ecole Polytechnique.